# Newton's Method, Galois Theory, and Something You Probably Didn't Know About $A_5$

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### References

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# **Outline**

- Newton's Method for Polynomials
- Generally Convergent
   Iterative Algorithms
- The McMullen Rigidity Theorem
- A Galois Theory of Generally
   Convergent Iterative Algorithms
- The Doyle/McMullen Theorem and the Quintic
- The Algorithm

# Newton's Method for Polynomials

Newton's Method doesn't always converge to a root.

**Example:**  $f(x) = x^3 - 5x$  gives

$$N(x) = x - \frac{f(x)}{f'(x)} = x - \frac{x^3 - 5x}{3x^2 - 5}.$$

N has the 2-cycle 1 
ightarrow -1 
ightarrow 1 
ightarrow

### Can do Newton's Method over C:

Here is Newton's Method for  $x^3 - 1$  over **C**:

Initial values which converge to 1 are shaded black.

### **Naive Guess:**

For a dense open subset of initial values, Newton's Method converges to a root.

### Counterexample: Let

• 
$$f(x) = \frac{1}{2}x^3 - x + 1$$
.

$$\bullet \ N = x - \frac{f(x)}{f'(x)}.$$

Then:

- ullet 0 o 1 o 0 o · · · under N.
- N'(0) = 0, so attracting 2-cycle.

Hence initial values near 0 or 1 do not converge to a root under Newton's Method.

# Generally Convergent Iterative Algorithms

In 1985, Smale asked for an iterative algorithm which:

- is rational in the coefficients of a polynomial, and
- converges generally to a root of the polynomial.

Generally convergent means that for  $f = x^n + a_1 x^{n-1} + \cdots + a_n$ ,

- ullet for  $(a_1,\ldots,a_n)$  in a dense open subset of  ${f C}^n$ , and
- for  $z_0$  in a dense open set of  $\mathbf{C}$ , the algorithm converges to a root of f.

In 1987, McMullen proved that an iterative, generally convergent algorithm doesn't exist when  $n \geq 4$ .

Also, for n = 3, consider

$$f(x) = x^3 + ax + b.$$

Then one can show:

- Newton's Method for f(x) is not generally convergent.
- Newton's Method for

$$\frac{f(x)}{3ax^2 + 9bx - a}$$

is generally convergent.

# Definition of a Generally Convergent Iterative Algorithm:

Consider a field K which is:

- ullet a finite extension of  ${f C}(t_1,\ldots,t_n)$ , or equivalently,
- the rational function field C(V)
   of an irreducible variety V.
   (An example is V = C<sup>n</sup>.)

**Definition:** A rational iterative algorithm is an element  $T \in K(z)$ , where z is a coordinate on

$$\mathbf{P}^1 = \mathbf{C} \cup \{\infty\}.$$

**Example:** For  $K = \mathbf{C}(a_1, \dots, a_n)$  and  $V = \mathbf{C}^n$ , Newton's Method is

$$N = z - \frac{z^n + a_1 z^{n-1} + \dots + a_n}{n z^{n-1} + \dots + a_{n-1}}$$

This is an element of K(z).

**Notation:** Let  $T \in K(z)$ . For most  $v \in V$ ,  $T_v \in \mathbf{C}(z)$  is defined. Thus  $T_v : \mathbf{P}^1 \to \mathbf{P}^1$ .

**Definition:** T is **generally convergent** if  $\{T_v^n(z)\}_{n=0}^{\infty}$  converges for (v,z) in a dense open subset of  $V \times \mathbf{P}^1$ .

# The McMullen Rigidity Theorem

**Theorem:** If T is generally convergent, then for v in a dense open subset of V, the maps  $T_v$  are all conjugate under PGL(2,  $\mathbb{C}$ ).

**Example:** For  $K = \mathbf{C}(t)$ ,  $T_t = z - \frac{z^n - t}{nz^{n-1}}$  is generally convergent. If  $\phi(z) = z/a$ , then

$$\phi \circ T_t \circ \phi^{-1} = T_{t/a^n}.$$

Note also that  $a = \sqrt[n]{t}$  implies

$$T_t = \phi^{-1} \circ f \circ \phi, \ f = z - \frac{z^n - 1}{nz^{n-1}}.$$

This will be useful later.

**Corollary:** No generally convergent iterative algorithm for general polynomial of degree  $\geq 4$ .

**Proof:** If such an algorithm existed for a general polynomial of degree n, then the roots would be conjugate under PGL(2,  $\mathbb{C}$ ).

More precisely, suppose f,g have degree n. If f has roots  $a_i$ , then we can find  $z_i$  with

$$T_f^n(z_i) \to a_i$$

If we have  $\phi \in PGL(2, \mathbb{C})$  with

$$\phi \circ T_f \circ \phi^{-1} = T_g,$$

then setting  $w_i = \phi(z_i)$  implies

$$T_g^n(w_i) \to \phi(a_i)$$

Thus the  $\phi(a_i)$  are the roots of g.

But the action PGL(2,  $\mathbb{C}$ ) on  $\mathbb{P}^1$  is only 3-transitive!

# A Galois Theory of Generally Convergent Iterative Algorithms

The **output** of T is the set

consisting of all  $(v,w) \in V \times \mathbf{P}^1$  such that

$$w = \lim_{n \to \infty} T_v^n(z)$$

for an open set of z's. Note that

$$\mathsf{Output}(T) \subset \{(v,w) \mid T_v(w) = w\}.$$

Let  $\overline{\text{Output}(T)}$  be the smallest variety containing Output(T).

**Definition:** A generally convergent iterative algorithm  $T \in K(z)$  is **irreducible** if  $\overline{\text{Output}(T)}$  is an irreducible variety. We denote its function field by  $K_T$ .

Such a T gives a finite extension

$$K \subset K_T$$
.

Let K' be the Galois closure of this extension and set

$$G = \operatorname{Gal}(K'/K).$$

Theorem: (Doyle/McMullen)

If T is as above, then there are:

- $f(z) \in \mathbf{C}(z)$
- $\phi \in \mathsf{PGL}(2,K')$
- $\rho: G \to \mathsf{PGL}(2, \mathbf{C})$  injective such that:
- $1) T = \phi^{-1} \circ f \circ \phi$
- 2)  $\{f^n(z)\}_{n=0}^{\infty}$  converges on a dense open set of  $\mathbf{P}^1$

### Furthermore:

- 3)  $f \circ \rho(g) = \rho(g) \circ f$  for all  $g \in G$ .
- 4)  $\phi^g = \rho(g) \circ \phi$  for all  $g \in G$ .
- 5) All irreducible generally convergent iterative algorithms arise this way.

**Example:** Let  $K = \mathbf{C}(t)$  and  $T = z - \frac{z^n - t}{nz^{n-1}}$ . Then we have:

$$K_T = K' = \mathbf{C}(\sqrt[n]{t}).$$

Furthermore:

$$\bullet \ f = z - \frac{z^n - 1}{nz^{n-1}}.$$

• 
$$\phi = \begin{pmatrix} 1/\sqrt[n]{t} & 0 \\ 0 & 1 \end{pmatrix} \in PGL(2, K').$$

• 
$$G = \{\sigma_i\}, \ \sigma_i(\sqrt[n]{t}) = \zeta_n^i \sqrt[n]{t}.$$

• 
$$\rho(\sigma_i) = \begin{pmatrix} \zeta_n^{-i} & 0 \\ 0 & 1 \end{pmatrix} \in PGL(2, \mathbf{C}).$$

**Definition:**  $K \subset L$  is **computable** if there are fields

$$K = K_0 \subset K_1 \subset \cdots \subset K_m$$

such that:

- ullet  $L\subset K_m$ , and
- There are generally convergent irreducible  $T_i \in K_i(z)$  such that  $K_{i+1} = (K_i)_{T_i}$  for all i.

**Definition:** A finite group is called **nearly solvable** if its Jordan-Hölder components are either cyclic or  $A_5$ .

# The Doyle/McMullen Theorem and the Quintic

**Theorem:**  $K \subset L$  is computable  $\iff$  Gal(L'/K) is nearly solvable, L' = Galois closure of  $K \subset L$ .

**Proof:** We can assume the Galois group is cyclic or  $A_5$ . By the Doyle/McMullen theorem, we need to find  $f, \phi, \rho$ .

**Cyclic Case:** Done by previous example!

 $A_5$  Case: Solve the quintic by iteration. First use Tschirnhaus transformations to reduce to

$$z^5 - 10Cz^3 + 45C^2z - C^2 = 0.$$

This is the Brioschi resolvent.

Next project the icosahedron onto  $S^2$  and then map to the plane via sterographic projection. Then consider

$$F(x,y) = x^{11}y + 11x^6y^6 - xy^{11}.$$

This is invariant under the binary icosahedral group and vanishes at the 12 vertices.

Then the rational function

$$f_{11}(z) = -\frac{\frac{\partial F}{\partial y}(z, 1)}{\frac{\partial F}{\partial x}(z, 1)}$$
$$= -\frac{z^{11} + 66z^6 - 11z}{11z^{10} + 66z^5 - 1}$$

has nice properties:

- $f_{11}$  commutes with  $A_5$ .
- The 20 face centers are the critical points of  $f_{11}$ .
- $f_{11}$ (face center) = center of antipodal face.

Thus the face centers give ten 2-cycles for  $f_{11}$ .

**Dynamical Systems Theory**  $\Rightarrow$  there is a dense open set of  $\mathbf{P}^1$ 

$$\{f_{11}^n(z)\}_{n=0}^{\infty}$$

converges to of the ten 2-cycles.

Then  $f = f_{11} \circ f_{11}$  is what we want! It remains to:

• Find  $\phi$ .

on which

- Compute  $T = \phi^{-1} \circ f \circ \phi$ .
- Relate to Brioschi resolvent.

This gives the following algorithm.

# The Algorithm

Define g(Z, w) to be the polynomial:

$$91125Z^{6} + (-133650w^{2} + 61560w - 193536)Z^{5} + (-66825w^{4} + 142560w^{3} + 133056w^{2} - 61440w + 102400)Z^{4} + (5940w^{6} + 4752w^{5} + 63360w^{4} - 140800w^{3})Z^{3} + (-1485w^{8} + 3168w^{7} - 10560w^{6})Z^{2} + (-66w^{10} + 440w^{9})Z + w^{12}$$

Define h(Z, w) to be the polynomial:

$$(1215w - 648)Z^4 + (-540w^3 - 216w^2 - 1152w + 640)Z^3 + (378w^5 - 504w^4 + 960w^3)Z^2 + (36w^7 - 168w^6)Z$$

To solve  $s^5 - 10Cs^3 + 45C^2s - C^2 = 0$ , proceed in five steps:

- 1) Set Z = 1 1728C.
- 2) Compute the rational function

$$T_Z = w - 12 \frac{g(Z, w)}{\frac{\partial g}{\partial w}(Z, w)}.$$

- 3) Iterate  $T_Z(T_Z(w))$  on a random starting point until it converges to a limit point  $w_0$ . Set  $w_1 = T_Z(w_0)$ .
- 4) For i = 0, 1 compute

$$\mu_i = \frac{100Z(Z-1)h(Z, w_i)}{g(Z, w_i)}.$$

5) Finally, for i = 0, 1, compute

$$s_i = \frac{(9 + \sqrt{-15})\mu_i + (9 - \sqrt{-15})\mu_{1-i}}{90}.$$

Then  $s_0$  and  $s_1$  are two roots of the Brioschi resolvent!